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Rotary Friction Welded C45 to 16NiCr6 Steel Rods: Statistical Optimization Coupled to Mechanical and Microstructure Approaches

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Abstract

This work represents the production of dissimilar friction welded joints between C45 carbon steel and nickel-chromium alloy steel 16NiCr6. Central Composite Response Surface (RSM) methodology, optical microscopy, scanning electron microscopy (SEM), backscattered electron diffraction (EBSD) and bending test were performed for this study. Physicochemical characterization was used to reveal the welded joint microstructures. The bending test was done in order to measure the ultimate bending strength (UBS). As a conclusion, regarding the optimization of the parameters, friction time and the rotation speed were the most effective parameters on the joint strength. These parameters revealed that the maximum bending strength of 1406.892 MPa can be obtained at a rotational speed of 2000 rpm, a friction pressure of 24.77 MPa and a friction time of 13 seconds. On the weld samples it was also noted that the particle size decreases significantly as the units of the parameters increase, which led to note that the optimization of these parameters converges towards an average particle size, where were found a good accommodation between hardness and young's modulus.

1. Introduction

Welding is often the weak point of these joint structures, especially if they are subjected to shock or vibratory loads. Some of these dissimilar joints require the use of input metals, and relatively expensive and difficult welding techniques. Most represent deficits in resistance to mechanical stresses caused by the melting of metals, which induces the brittleness of the weld bead [1–4]. Generally, medium carbon steels have average or poor weld-ability, although their very diverse use in the construction industry, due to their high mechanical strength. C45 and 16NiCr6 quality steels are extended and used in various industrial applications such as shipbuilding and the automotive industry. In fact, rotary friction welding (RFW) allows similar and dissimilar joints to be produced, which is today a solution for obtaining high welded joints [5–8]. Hence, RFW used for production of vehicle parts such as drive shafts, engine valves, pumps and compressor [9].

RFW creates joining by elevation of the temperature between the two surfaces in contact under effect of rotation speed and pressure, one of the piece is held in the stationary part while the other is chuck in moving part, the two pieces being in contact of each other until the rotation stopped rapidly, this period is called friction phase, then the pressure amplified to terminate the process and finish of welding joint, this period of time is called forge phase [10]. This technique has a several advantages such as: the absence of smoke and sparks, no filler metal, no shielding gas, a high welding rate for a short welding time, excellent mechanics, metallurgical properties, and a very resistant weld joint [8]. Contact between the two parts will trigger a flash, which will remove impurities and oxides from the interface which will subsequently promote the creation of a weld with excellent chemical and physical properties [7]. Thus, the thermal affected zone (TAZ) will expand to a lower thickness in friction welding compared to conventional welding [11].

Many studies on RFW and their parameters have been forgotten through experimental and analytical methods in trying to optimize favorable welding conditions. The basic parameters of RFW are: rotational speed V (rpm), friction time (s), friction pressure (MPa), forging time (s) and forging pressure (MPa). Table 1 presents a review of the literature for some of the previous authors operating conditions in RFW.

Table 1
Some welding parameters of previous research.

Ref	Materials	D (mm)	V (Rpm)	P _{friction} (MPa)	P _{forging} (MPa)	Friction time (s)	Forging time (s)
[12]	SUS304-SUS304	25	500-900-1500	60-80-100	*	0.2 to 15	*
[13]	304SS-304SS	25	1500	80	80	*	6
[11]	AISI 1040-AISI 1040	10–12	2095	*	*	16–18	*
[8]	AISI 1010-ASTM B22	20	2500	20	22	1–8	*
[14]	AISI 304L-4340 steel	12	1500 to 2500	40	60	5	*
[7]	AA1050-AISI304	14.8	3200	2.1	1.4	7–32	2
[15]	AISI 304-AISI 1060	20	2000	30-40-50	50–70	5	*
[16]	AISI 316-AISI 304	12	3000	130	260	6.5-8.5-10	5
[17]	AISI 316-AISI 316	12	3000	130	*	6.5-8.5-10	*
[18]	AISI 304-AISI 304	12	3000	130	260	6.5-8.5-10	5
D: sample diameter.							
N: rotation speed in road per minute.							
*: information not mentioned by the authors.							

For optimizing friction welding parameters, there are two methods for optimizing these parameters. First one depends on single factor, changing one condition and fixing the others, while second one relies on the statistical method [19]. Several researchers used a design of experiments approach (DOE) in different applications [20–22] including a response surface methodology (RSM), when a response or more responses of interest are influenced by many parameters.

However, Akbar Heidarzadeh [23] used response surface methodology of RSM for friction-stir welding. The results show that the most effective parameters for joint elongation and strength were tool rotational force and forging force, respectively. Optimization of these parameters showed that the maximum elongation of 55% and strength of 318 MPa can be achieved at a rotational speed of 1000 rpm, advance speed of 58 mm / min and an axial force of 03 kN. S.T. Selvamani and K. Palanikumar [24] have performed of RSM on the production of AISI 1035 carbon steel rods to optimize RFW parameters and achieve maximum tensile strength. The ANOVA method showed that a maximum expected tensile strength of 548 MPa could be achieved under welding conditions of 1464 rpm rotational speed, 03 seconds friction time, 86 MPa friction pressure, 03 seconds forging time with 86 MPa forging pressure. In the other hand, some works have studied RFWs of steels, similar and dissimilar joints [25–27].

Based on our knowledge, there is no study in open literature which reports the use of design of experiments and especially the full factorial approach to investigate the influence of parameters to measure the Ultimate Bending Strength (UBS) using a proper experimental design of carbon steel C45 with nickel-chromium alloy steel 16NiCr6 which improves the ultimate bending strength (UBS) of welded joint in first place. and provide the best clarification of the origins of the improvement in mechanical performance. Subsequently, the materials were characterized and evaluated by micro-structural approach and mechanical behaviour as a function of changes in RFW parameters using optical microscope (OM), SEM, electron backscatter diffraction (EBSD) and its effect on most significant parameter of welded joint.

2. Experimental Procedure

Medium carbon steel (C45) and Nickel chromium alloy structural steel for case hardening (16NiCr6) rods with 12 mm in diameters and 45 mm in length were used for present study. The chemical compositions and mechanical properties of the base metals are presented in Tables 2 & 3 respectively. The microstructure of the C45 and 16NiCr6 showed both a ferrite and pearlite structure with a difference in proportion.

Table 2
Chemical composition of the base metals (wt%)

Material	C	Mn	Si	P	S	Ni	Cr
C45	0.45–0.50	0.7	0.3	≤0.035	≤0.035	-	-
16NiCr6	0.14–0.17	0.15–0.40	0.40–0.60	-	-	1.40–1.70	1.40–1.70

Table 3
Mechanical properties of the base metals

Material	HV 0.1	Rm(N/mm ²)	Re(N/mm ²)	A%
C45	180–210	560–620	275–340	14–16
16NiCr6	200–230	650–1400	470–800	9–11

Welding operations were performed using RFW machine [16–18]. It is has three phases AC and 3.5 kW power of motor with brake system, it supplies rotational speeds up to 3000 rpm and maximum pressure of 300 MPa. C45 test pieces were chucked in rotary part and 16NiCr6 were kept in stationary once. The objective of design of experiments approach is to simultaneously optimize the levels of these parameters in order to obtain the best system performance. It is a set of statistical and mathematical techniques that work by fitting a polynomial system equation to experimental data, which describes the behaviour of a set of data in order to make statistical predictions [28]. The following independently controllable process parameters were identified for the experiments: friction pressure (F), friction time (T) and rotational speed (V). Constant forging pressure (70 MPa) and forging time (3 s) are used in this study. The working ranges of all the selected parameters were determined by carrying out tests. One of the parameters was modified, while the others were kept at constant values. The working range of each welding parameter was determined by checking that the weld was free of visible defects. For experimental design was used JMP 13 software with ANOVA methods, where the upper and lower limits with different levels of the identified process parameters are shown in Table 4. The selected design matrix is a central composite factorial design consisting of 16 sets of coded conditions [29]. All friction welding variables at the intermediate level (0) are the centre points and combinations of each of the welding variables at their lowest (-1) or highest (+1) level.

Table 4
Factors and levels used in the study

Parameter	Notation	Unit	Factor levels		
			-1	0	+1
Rotation speed (X_1)	V	rpm	2000	2500	3000
Friction pressure (X_2)	F	MPa	20	30	40
Friction time (X_3)	T	s	9	11	13

After welding, a flash of metal is observed for all specimens as shown in Fig. 1, this indicated that the surfaces of the joined materials were softened and plastically deformed, hence their solid-state welding has occurred [30]. This behaviour could be occurred due to increase in temperature induced by the elevation of friction time which softened the steel and favoured its plastic deformation. Figure 1a, shows view of welds from different parameters used present RSM model. The weld joints show similar macroscopic aspects with different flash formation size as the change of the welding parameters from minimum to maximum units. Flash formation in the rotary friction welding process was due to increase in parameters and the generated heat which was higher at the periphery than in the central area of the welded joint [31].

Mechanical bending test based on ASME BPVC Section IX- 2017 (PP 38) was conducted to show the flexion properties and ultimate bending strength (UBS) of the joints. For this purpose, the longitudinal flexion samples were cut with Molybdenum wire perpendicular to the weld line with geometry of 40 mm

(length), 6 mm (width), and 3 mm (thickness), the schematic of the bending specimens is illustrated in Fig. 1d. Bending tests were conducted on TIRA test 2300 equipment with a bending rate of 1 mm/min and automatically stop at 8mm of bending. It is notable that five bending tests were carried out for each FRW parameters. The 16 experimental runs allowed for the friction welding parameters combination, the experimental and predicted ultimate Bending strength (UBS) and the graphs are summarized in Table 5 and Fig. 2 respectively.

Table 5
Design layout including experimental and predicted values

No	Samples	Coded value of parameters			UBS (MPa)		crack
		X ₁	X ₂	X ₃	Experimental	predicted	
1	S10	1	-1	-1	1295	1288.50862	
2	S6	-1	1	-1	1109	1096.80862	
3	S8	0	1	0	1144	1165.16552	
4	S4	0	0	0	1202	1223.06897	
5	S5	-1	0	0	1267	1245.16552	
6	S16	1	0	0	1302	1311.76552	
7	S1	-1	-1	-1	1134	1145.90862	
8	S3	0	0	-1	1158	1174.36552	
9	S7	1	1	-1	1265	1255.40862	*
10	S14	1	-1	1	1358	1373.20862	
11	S2	0	0	0	1220	1223.06897	
12	S15	-1	1	1	1323	1332.50862	
13	S12	-1	-1	1	1386	1398.60862	
14	S13	0	-1	0	1248	1214.76552	
15	S9	1	1	1	1332	1323.10862	
16	S11	0	0	1	1363	1334.56552	*
* There was a fracture of the sample.							

The microstructure of the joints was first examined by using an optical microscope (OM). The OM sample were sectioned from the joints parallel to the direction of welding Fig. 1c, and then prepared by mechanical polishing until using OP-S 0.04um, chemical etching was done with a solution of 1ml nitric acid in 100ml ethanol. SEM and EDX ZEISS Gemini SEM 300 were used to observe the fractured

surfaces. For EBSD used a SEM Jeol JSM 7000F on two samples S3(00–1) and S11(00 + 1) were prepared by ionic polishing in order to study the evolution of the grain structure.

Nano-indentation measurements were done by Anton Paar NHT-3 nano-indenter with a Berkovich tip using a 50 mN applied load. The indenters were carried out in the welding centre, while the hardness and Young's modulus were automatically calculated taking into account the standards of the instrumented indentation using the Oliver-Pharr method [32]. Scratch tests were carried out on Bruker UMT equipment, across the welding interface at a constant load of 20 N with a scratch length of 10 mm and a speed of 0.1 mm/s. While Vickers microhardness $H_{V0.1}$ was achieved by WILSON VH3300 with 70 points of measurements start from C45 to 16NiCr6 crossing the welding interface.

3. Results And Discussion

3.1 Factorial design of experiments:

3.1.1. Model fitting

The evaluation of effective process variables on the UBS (MPa) were performed based on the Composite Central design (CCD) matrix with two replicated points. The design points, experimental and predicted results of (UBS) are represented in the Table 5.

To minimize the effects of uncontrolled factors, the experiments were performed in a random sequence too. Present study have found that the relationship between Ultimate bending strength (UBS) of the friction welded samples joints is a function of the friction welding parameters such as a Rotational speed (X_1), friction pressure (X_2) and Friction time (X_3) which can be expressed as [24]:

$$UBS = \{X_1; X_2; X_3\} \quad (1)$$

The second-order polynomial equation is used to represent the response surface Ultimate bending strength given by:

$$UBS = b_0 + \sum b_i X_i + \sum b_{ii} X_i^2 + \sum b_{ij} X_i X_j \quad (2)$$

For three factors, the chosen polynomial model can be expressed as:

$$UBS = b_0 + b_1(X_1) + b_2(X_2) + b_3(X_3) + b_{12}(X_1 X_2) + b_{13}(X_1 X_3) + b_{23}(X_2 X_3) + b_{11}(X_1^2) + b_{22}(X_2^2) + b_{33}(X_3^2) \quad (3)$$

Where (b_0) is the average of the responses and $b_1, b_2, b_3, \dots, b_{33}$ are regression coefficients [33] that depends on the respective linear, interactive, and squared terms of the factors. The significance of each coefficient is determined by 'F' and 'p' values, which are listed in Table 6.

Table 6 ANOVA analysis of UBS (MPa)

Source	Sum of squares	D _F	Mean square	F-ratio	p-value
Model	111129.13	9	12347.7	15.9716	0.0016*
Error	4638.62	6	773.1		
C.Total	115767.75	15			

*p < 0.05

The value of the coefficient is calculated using the Design Expert Software. The quadratic model proved to be adequate for predicting the response given by the following Equations:

$$UBS \text{ (MPa)} = 1223.06 + 33.3 * X_1 - 24.8 * X_2 + 80.1 * X_3 + 4 * (X_1 * X_2) - 42 * (X_1 * X_3) - 4.25 * (X_2 * X_3) + 55.39 * X_1^2 - 33.1 * X_2^2 + 31.39 * X_3^2 \quad (4)$$

In Eq. (4) can show the interactions between variables. They have significant effects on the response; the results are therefore presented and discussed. The statistical significance of Eq. (4) is presented in Table 7. From Table 6, respectively the terms mean square, degree of freedom (D_F) and sum of squares are defined as the variance estimation of the model, the number of model and total sum of squares for model. The ANOVA (F-test) shows that the second order model (quadratic polynomial) corresponds to the experimental data also. The p-value is a quantitative measure to report the result of a hypothesis test. This is the probability that the statistical test is at least as extreme as those observed since the null hypothesis is true. Based on the results of the Fig. 3, R² it was equal to 0.96 indicating the model to satisfy well the response [24].

The degree of freedom (D_F = 15) in Table 6 indicates the total number of model terms, including the intercept minus one. It is clearly that the model is highly significant, as suggested by the model F-value (15.9716) and a low probability value (p-value = 0.0016). If p-value is less than or equal to the chosen significance level alpha value of 0.05, the test suggests that the observed data are inconsistent with the null hypothesis. Therefore, it's must be rejected and the factor effect is significant [34]. It appears from Table 7 the linear effects of rotation speed; friction pressure and time are significant. The same trend was observed for the interactions effects between these factors, which confirms that the model is highly significant with the p-value of 0.0016 < 0.05 [35-37] and F-value of 15.9716 cited in ANOVA analysis in Table 6.

In current study have analyzed the results obtained which appear in the Table 7, it can be conclude that friction time (X₃) is the most important parameter for the overall UBS (MPa) with a high t-ratio: 9.11, the parameter exerts a stronger influence on the response (UBS). Secondly, rotation speed can be the second important influencer parameter phenomenon with a t-ratio: 3.79. Friction pressure was the least significant parameter with a t-ratio: -2.82. The interactions of (X₁ and X₃) (with a high t-ratio: -4.27) was the most significant compared to the other combinations (X₂ and X₃) and (X₁ and X₂). The latter was the

least significant (with a t -ratio: 0.41). The negative sign means that the factors and the response are inversely proportional.

Table 7 Estimated regression coefficients.

Parameter	Estimate	Standard Error	t -ratio	p -value
Intercept	1223.069	13.16365	92.91	0.0001*
X₁(V)	33.3	8.79	3.79	0.0091*
X₂ (F)	-24.8	8.79	-2.82	0.0303*
X₃ (T)	80.1	8.79	9.11	0.0001*
X₁*X₂	4	9.83	0.41	0.6982
X₁*X₃	-42	9.83	-4.27	0.0052*
X₂*X₃	-4.25	9.83	-0.43	0.6806
X₁* X₁	55.39	17.12	3.23	0.0178*
X₂* X₂	-33.10	17.12	-1.93	0.1014
X₃* X₃	31.39	17.12	1.83	0.1164

On the other hand, the difference between experimental and predicted values is illustrated on UBS in Fig. 4. There are points below and above straight line called point of line zero; the positive values observed on the residual plot indicate a low predictive result. While, negative values imply that the prediction was high; a value of zero means that the prediction is accurate since there is a total superposition between experimental and predicted values. The residual plot for UBS following Eq (4) shows a random pattern. This indicates that the distribution of residuals for the response approximately follows the fitted normal distribution.

3.1.2. Interaction plots

Fig. 5 illustrates possible positive and negative effects of two variables interactions, respectively among the three parameters on UBS response. The non-parallel curves show the presence of interaction that can be estimated between rotation speed “X₁” and friction time “X₃” equal to 0.0052, which means that the higher values of rotation speed affects UBS capacity when friction time is high and equal to 9 s.

In addition, the effects of interactions such as rotation speed “X₁” and friction pressure “X₂”, friction pressure “X₂” and friction time “X₃” are negligible due to parallel curves, which indicate the friction pressure x2 is the least significant or non-significant in the presence of other parameters simultaneously.

These results confirm the previous finding obtained from Table 7, related to each parameter of influence on UBS process. Consequently, and in order to better understand the relationship between the three variables studied and the response which can be related to UBS, a cubic graph is presented in Fig. 6.

The cubic graph demonstrates that increasing rotation speed V from 2000 rpm to 3000 rpm and friction pressure from 20 MPa to 40 MPa considerably decreases UBS from 1288.51 MPa to 1145 MPa and 1288.51 MPa to 1255.41 MPa. The absence of parameter input of x_2 (friction pressure) and speed of rotation of x_1 on the weld joint could be explained in the survey. Consequences of an increase in two previously located parameters influence the increase in the welded joint resistance until it reaches its limit and then decreases again. The reason is increased plastic deformation resulting from the application of excessive pressure and rotational speed [7].

3.1.3. Response surface methodology (RSM)

To further illustrate and discuss the effect of each factor and the interactions between these factors we were referred to the 3D response surface plots which were drawn as three dimensional plots of two factors while the other factor was kept constant. The 3-dimensional response surface for UBS (MPa) is shown in Fig. 7.

Fig. 7a represents UBS for different values of rotation speed (X_1) and friction pressure (X_2) for a constant friction time (X_3). It is clearly that the response (UBS) increases when friction pressure (X_2) increase independently. Fig. 7b illustrates combined effect of rotation speed (X_1) friction time (X_3) for a constant value of friction pressure (X_2) on UBS response. It can be seen that UBS increases as friction time (X_3) decreases at friction pressure values. Therefore, Fig. 7c shows effect of friction pressure (X_2) and friction time (X_3) on UBS at constant value of rotation speed (X_1). It can be seen that at high values of friction time t , UBS increases independently. As reported in previous work [15], with increasing friction time, hardness and tensile strength are increased. Those are influenced by augmentation of young's modulus and impact of friction time on welded joint also recognized in the micro-structural observation. Fig. 7 indicates UBS optimization results which can be achieved at lower values of rotation speed (X_1).

3.1.4. Optimal design conditions using the desirability method

The main object of this study was to find the optimal conditions in which UBS will be maximized, that desirability function was well used by Suich and Derringer in 1980 to solve the problems related to the optimization of industry-related multiple responses which have been applied in many studies [38-40]. Fig. 8 illustrates the prediction profiler function of studied parameter, it can be concluded that optimized conditions were rotation speed of 2000 rpm, friction pressure of 24.77 MPa and friction time of 13 s for a predicted response UBS of 1406.892 MPa with a desirability value of 0.991859.

3.2 Experimental results:

3.2.1 Micrographic and metallographic analysis:

Fig. 9 shows an optical micrograph of welded joint for different zones, thermal affected zones (TAZ) and thermo-mechanical affected zones (TMAZ). As can be seen in Fig. 9, the welded joints were perfectly bonded; no cracks, low pores and no defect are observed. The grains are different in each affected zone, mainly resulting from the variation in temperature and pressure distribution. The grains are not uniform, elongated in the TAZ as shown in Fig. 9a & 9c, and refined in TMAZ as shown in Fig. 9d & 9f, cause of pressure application and heat due to thermo-mechanical action [41]. Furthermore, a reduction in ferrite and pearlite rate in each of steels is observed in compared to the base metals [24]. Ferrite/pearlite ratio remained the same in both steels after welding, i.e., the proportion of ferrite is predominant in C45 and conversely the rate of pearlite is higher in 16NiCr6.

Two flows are observed in the vicinity of the welded joint Fig. 9b & 9e; the connection line of two steels plays role of an inverse axis of symmetry. Noticed also, that the absence of interface is enrolled by existence of continuity; within a good junction between the samples, the grain size has decreased significantly compared to TMAZ, which is a direct consequence of a dynamic recrystallization (DRZ) of the grains [42-43]. Indeed, the welding zone consists of equiaxed grains as a reason of sufficient DRZ is occurred [44].

Fig.10 represents SEM and EDX analysis performed at the central region of bonding interface and also at the ends of welded joint. The results are similar, with little variation in diffusion layer between the main chemical elements of C45 and 16NiCr6 steel. Fig. 10a reveals most relevant advantages of friction welding can be easily deduced. In fact, a significant reduction in the number of pores compared to base metals can be seen, probably a consequence of high plastic deformation [45]. Fig. 10b shows inter-diffusion between Ni, Cr, Si and Mn characterizing the diffusion as the main bonding mechanism in the rotary friction welding process. The analysis records clearly diffusion of Cr and Ni through the interface from 16NiCr6 to C45. As a result of the diffusion, a gradual reduction of Cr and Ni in 16NiCr6 side adjacent to the interface and increasing of Cr and Ni in C45 side. Conversely is occurred for Si and Mn while these two last elements decrease in C45 interface side and increase in 16NiCr6 side, this result is in adequacy with references [7].

Fig. 11 shows EBSD map of welded joint of two samples S3(00-1) and S11(00+1). The maps show red, green and blue colour present 001, 011 and 111 planes respectively. It can be seen that the green colour dominates in the EBSD map for S3 welding parameters with low friction time and blue colour for S11 in high friction time, Fig. 11a & 11b respectively, which indicates that the grain orientation mainly concentrates in the normal direction of crystallographic plane {101} for S3 and {111} for S11.

For low parameters the grain size is not uniform than for high parameters, no special high-density orientation distribution. The statistical result of grain indicates that the proportion of average diameter grain size is 3.32 μm in parameters with low friction time (00-1) and 2.15 μm for parameter with high friction time (00+1). The origin of finer grains in the high friction time input joint can be attributed to micro-structural evolution during RFW.

3.2.2 Mechanical behaviour

RSM study shows that the most significant parameter influencing UBS is the friction time. In this perspective present work studied the mechanical behaviour of welded joint at the parameters of (0.0.-1) (0.0.0) and (0.0.+1), to demonstrate the contribution of friction time to weld joint behaviour. Valuable information's on mechanical behaviour are provided using the measurements of hardness, wear and nano-indentation at different stages of the friction time.

Vickers micro-hardness distributions in specimens previously selected are shown in Fig. 12a. The measurements were carried out from C45 side to 16NiCr6 side. As expected, the micro-hardness reaches maximum values close to the interface and decreases very rapidly from TMZA until base metal. Fig. 12a shows a comparison between welded specimens with high, low and medium friction time, as observed from this figure can recognize an increase of micro-hardness from t: 9 s Hv 360 ± 10 to t: 11 s Hv 430 ± 10 and then decrease in t: 13 s to achieve Hv 350 ± 10 where the base metal on both C45 and 16NiCr6 were approximately Hv 200 ± 10 for C45 and Hv 220 ± 10 for 16NiCr6, this increasing may have caused by micro-structural evaluations around the interface, diffusion of elements on the sides, work hardening, dislocation and refinement of grains.

The literature demonstrates a similar hardness profile for dissimilar material couples [46]. Microhardness at t: 13 s friction pressure, represent approximately 65% up than microhardness of the base metals which is very low compared to other fusion welding process, [24]. The decrease in hardness at t: 13 s which can be attributed to the decrease in temperature generated. In fact, after the plastic deformation, a reduction in friction is generally observed. The same behaviour has seen in Fig. 12c. The nano-indentation applied on the same samples shows a similar behaviour where the displacement into surface at t: 11 s is less than those at t: 9 s and 13 s, which leads us to suppose that the hardness at 9 and 11 s friction time is similar.

Nevertheless, Fig. 12d shows better understand the impact by increasing of welding time on the mechanical behaviour. Noticed there is a clear increasing of young's modulus of 260 GPa compared to the lower friction times, t: 11 s is 210 GPa and t: 9 s is 230 GPa. Fig. 12b illustrates three different scratch profiles. It can be seen at the interface with substrate various coefficient of friction with change of welding time, also observed a deep fluctuations in both C45 and 16NiCr6 sides that may be related to presence of pores in that areas and can easily notice the decrease in these fluctuations at the weld interface, which maybe equates to decrease in that pores and confirms with Fig. 10a. Thus, close to the interface, a low deformation is observed due to the presence of TAZ, which reveals a high microhardness and that for all welded samples.

Regarding to the behaviour as a function of friction time variation, noticed that the friction coefficient decreases in the welded zone, which can be explained by high grains refinement. On the other hand, the variation of friction coefficient shows an increase at t: 11 s, which leads us to suppose that the grains have coalesced, this coefficient relapses at t: 13 s, due to grain disintegration formed after t: 11 s.

Bending fracture surface micrographs by SEM were performed on specimen S11 (0.0.1) and S7 (1.1.-1). As presented in Fig. 13, bending specimen S11 shows that the fracture mostly takes place at rotary part

(C45 side), with elongated grain structure at fracture zone, the SEM observation indicates a river like pattern that commonly attributed to the brittle fracture [47]. The elongated structure at some region shows ductile fracture [48]. Fig. 13a shows detailed view of the fracture surface in which the structure is elongated and dislocated, which's remarkable from one zone to another. Fig. 13b and 13c illustrate fracture surface for steels are with half bubbles or cups, the latter are characteristic of a ductile fracture and are formed by growth of cavities in the material. Ductile fracture is preceded by significant plastic deformation, often resulting in cups linked to decohesion around inclusions that act as initiation of fracture. Fracture surfaces show the presence of several cups of sizes between 5 to 10 μm . These cups extend in the tensile direction. These cavities gather and coalesce in order to accelerate the fracture.

4. Conclusion

In this study, the impact of Rotary friction welding parameters (rotational speed, friction pressure and friction time) on the ultimate bending strength MPa of welded C45 to 16NiCr6 are investigated using RSM technique, microstructural analyses and mechanical tests. The main conclusions obtained can be summarized as following below.

- Studying the impact of welding parameters and trying to optimize, the RSM results shows the most effective parameters on the UBS of the joints is friction time, respectively. However, the combined rotary friction welding parameters impact on the UBS of joints differently regarding to microstructure change. 3D response surface interaction reveals that normal friction time – friction pressure interaction is the most influencing in UBS. On the other hand, by RFW at a rotational speed, friction pressure, and friction time of 2000 rpm, 24.77 MPa, and 13 seconds, the maximum value of 1406.89 MPa can be obtained for UBS of the joints.
- Microstructural properties of welding joint at low and high friction time show a great difference in the mechanical behaviour regarding to the deformation of grain which become more refined by increasing of friction time, this behaviour results from it a clear increase of young's modulus which reaches 260GPa at $t = 13$ seconds representing an augmentation of 13% compared to $t = 11$ seconds and 23% compared to $t = 9$ seconds.

Declarations

Funding (information that explains whether and by whom the research was supported) Not applicable

Conflicts of interest/Competing interests (include appropriate disclosures) Not applicable

Availability of data and material (data transparency)

The authors confirm that the data supporting the findings of this study are available within the article. The raw data that support the findings of this study are available upon a reasonable request.

Code availability (software application or custom code)

Not applicable (jmp 13 design of experiments “free version”)

Ethics approval (include appropriate approvals or waivers) Not applicable

Consent to participate (include appropriate statements)

The authors state that the work was carried out in collaboration with all members

Consent for publication (include appropriate statements)

The authors agree and wish that the paper will be published in your journal

Authors' contributions (optional: please review the submission guidelines from the journal whether statements are mandatory)

Authors contribution **Youcef Belkahla**: conceptualization, experimental work, data curation, and writing (original draft preparation). **Azzeddine Mazouzi**: investigation, experimental work, reviewing, and editing. **Seif El Islam Lebouachera**: software and analysis of all the obtained raw data of response surface methodology. **Ammar Jabbar Hassan**: methodology, reviewing and editing (final draft), review, and editing. **Martin Fides**: supervision and project administration. : validation. **Pavol Hvizdoš**: methodology, validation, and involved in the discussion. **Billel Cheniti**: methodology and reviewing **Djamel Miroud**: project administration.

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Figures

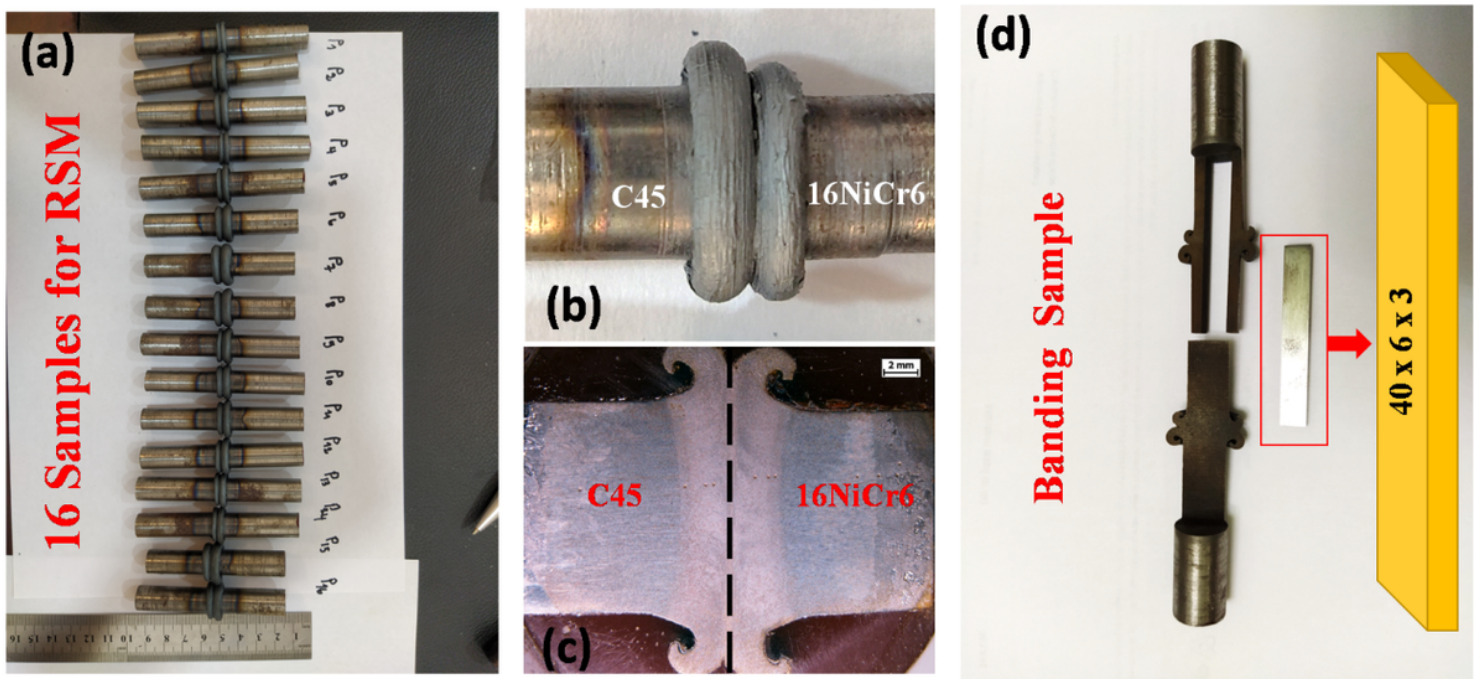


Figure 1

Photographs of friction welded joints and tested specimens. a 16 samples for RSM, b flash form of sample, c macrograph of welding joint, and d bending sample.

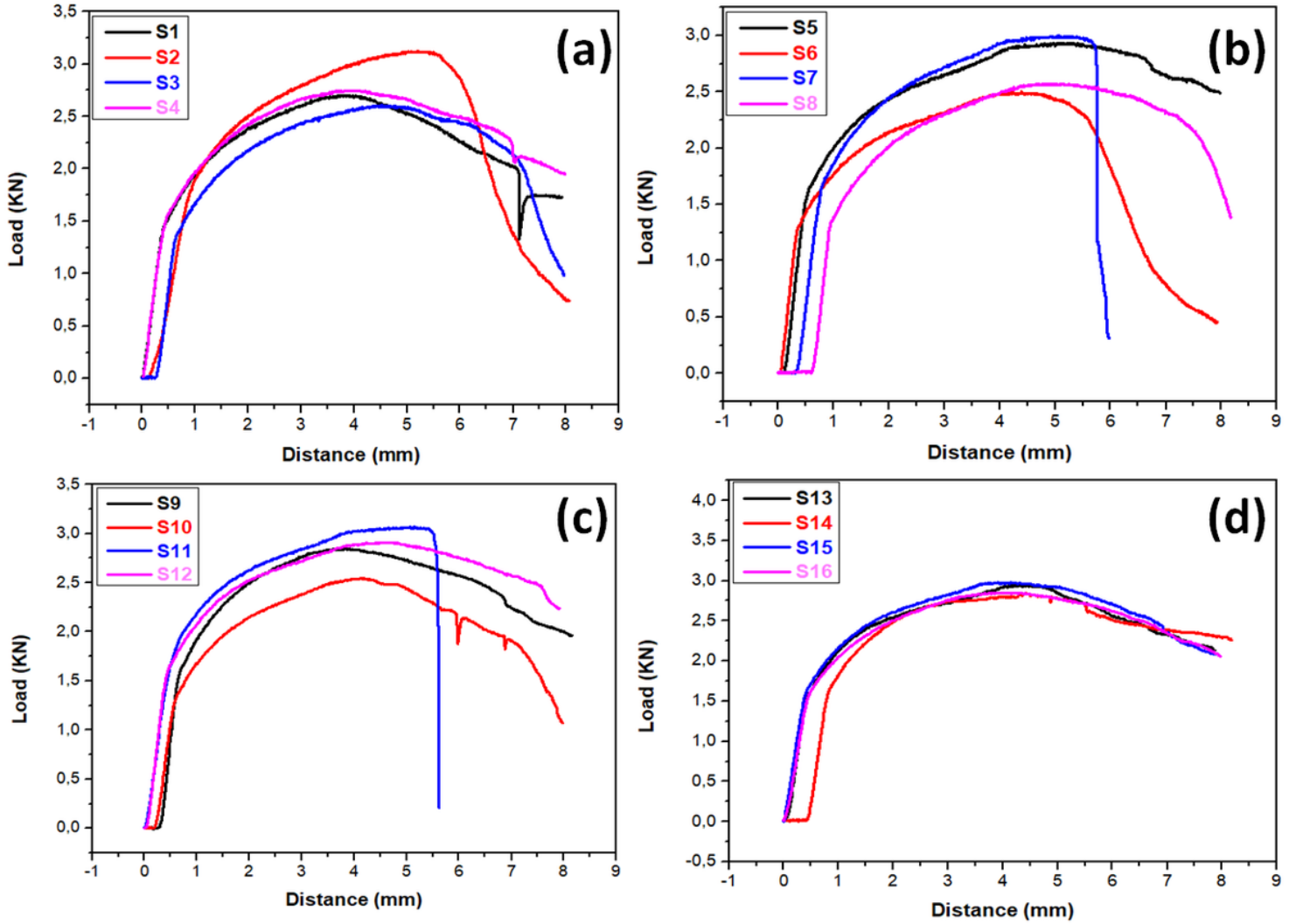


Figure 2

Load- displacement curves for bending test for all samples. a S1-S4, b S5-S8, c S9-S12, and d S13 S16

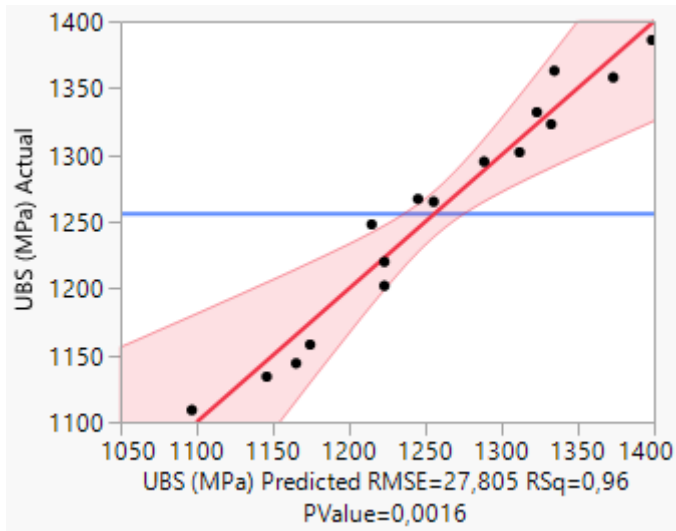


Figure 3

Plot of predicted versus experimental responses of UBS (MPa)

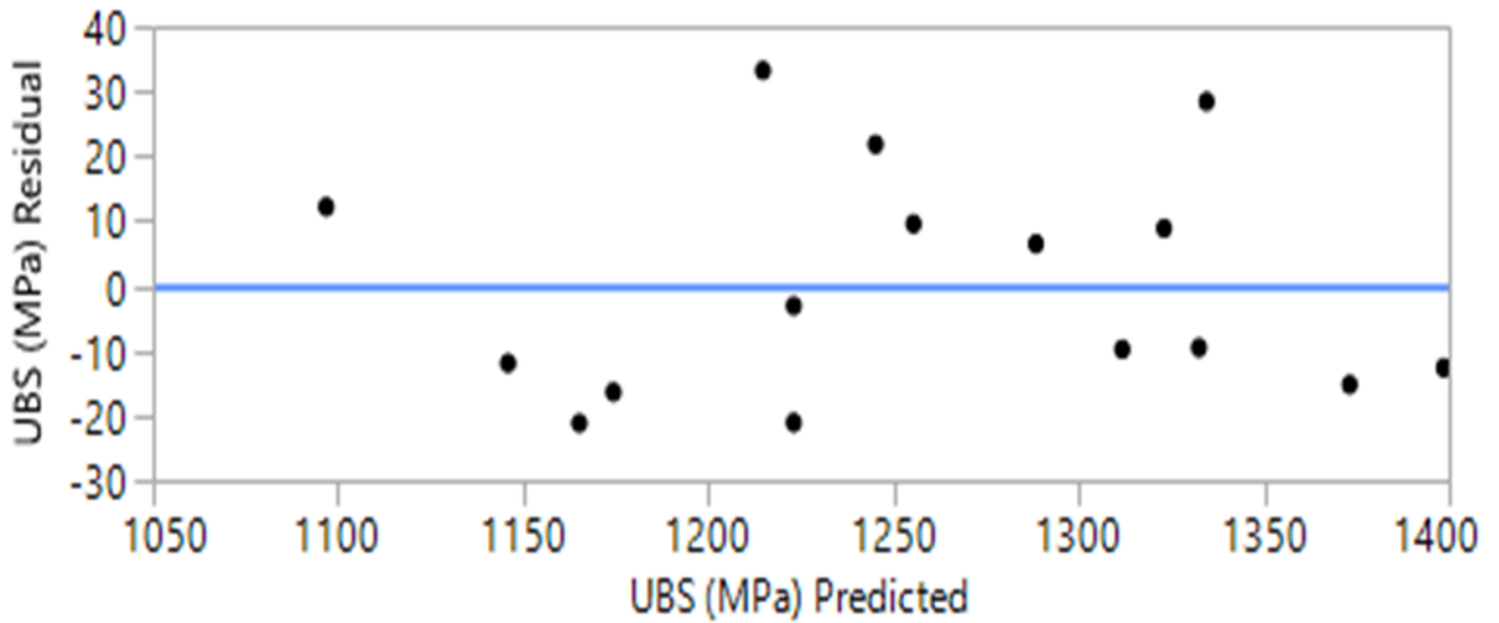


Figure 4

Residual plot of Ultimate bending strength UBS in MPa in the model

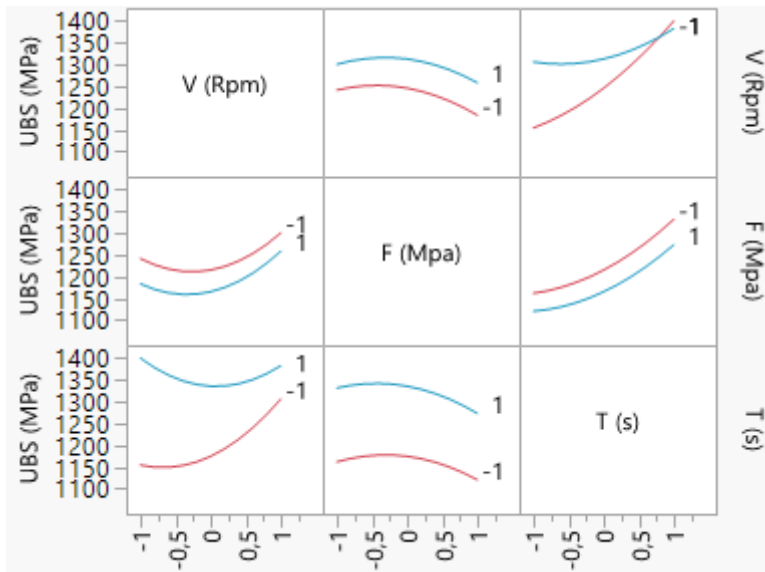


Figure 5

Interaction effect plots of the UBS (MPa) vs. studied parameters

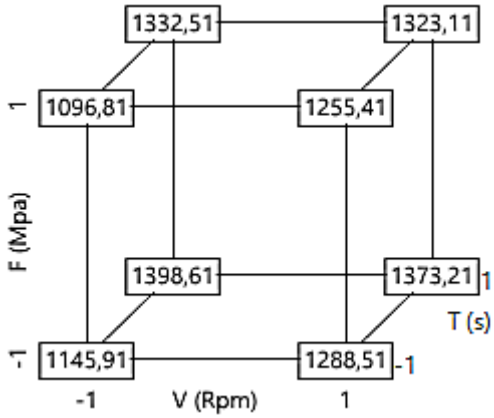


Figure 6

Cube of USB (MPa) considering the interactions

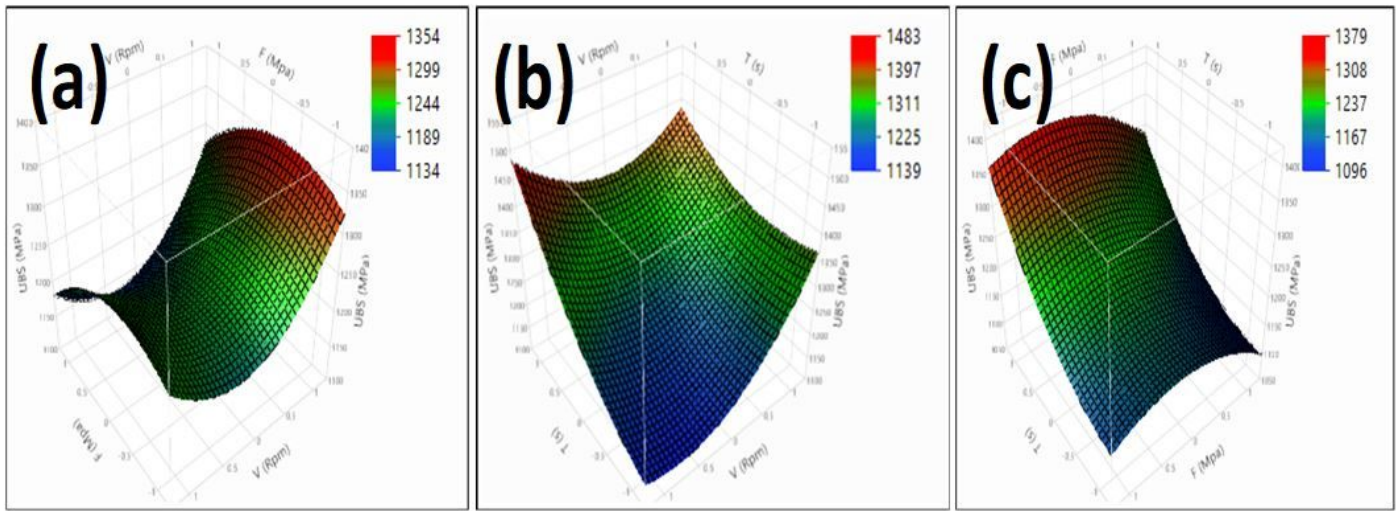


Figure 7

Response surface contour (3D) of UBS (MPa) showing combined effect of three welding parameters (x1, x2, x3)

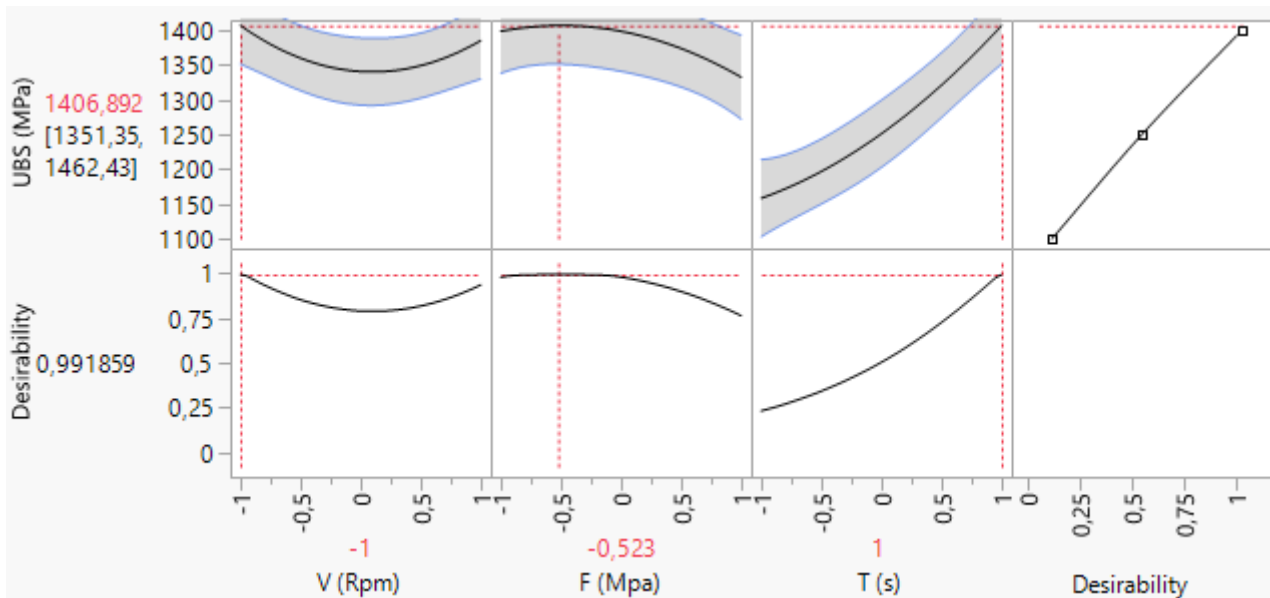


Figure 8

Prediction profiler of Ultimate Bending Strength MPa function

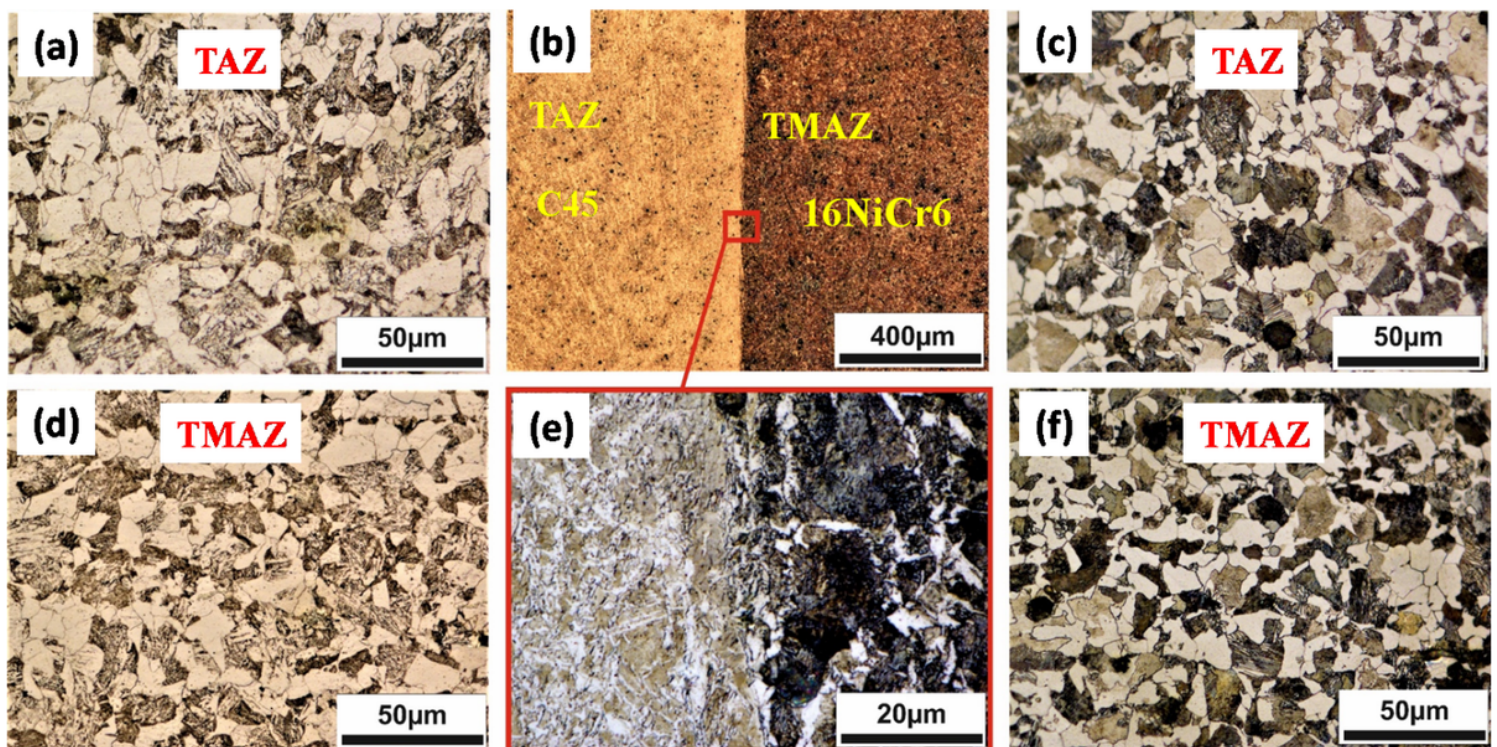


Figure 9

Optical micrographs for welded joint. a TAZ for AISI 1045 side, b global micrograph shows welded joint, c TAZ for 16NC6 side, d TMAZ for AISI 1045 side, e dynamic recrystallization zone DRZ, and f TMAZ for 16NC6 side

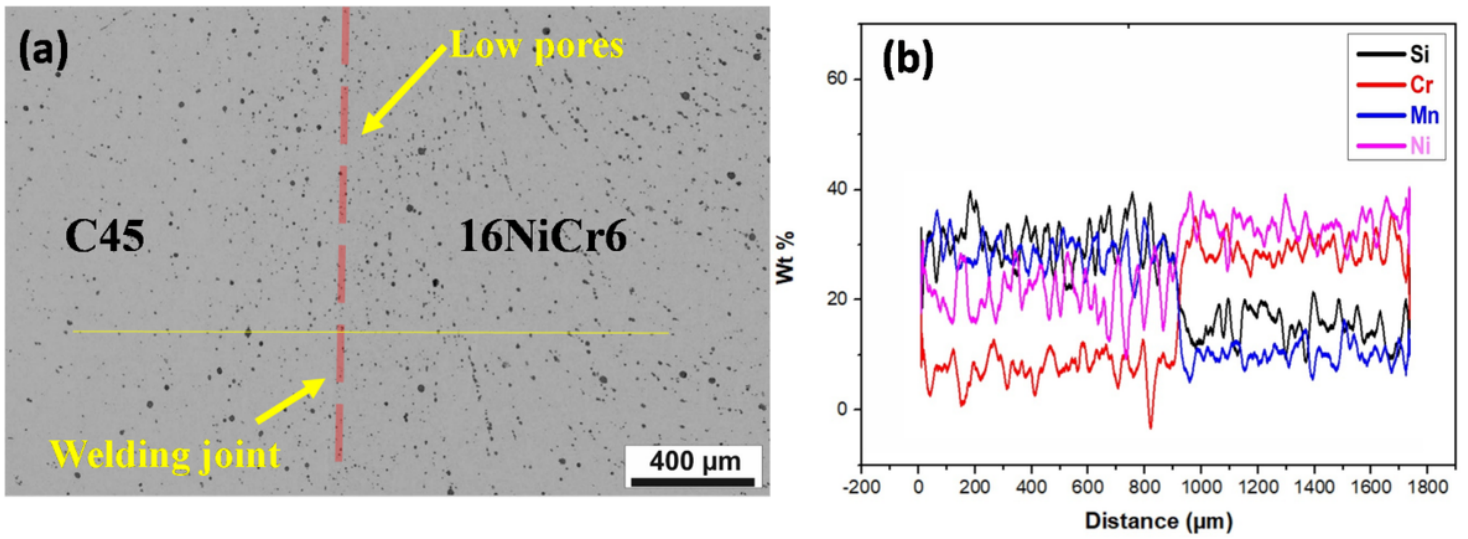


Figure 10

SEM images and EDS micrograph for welded joint

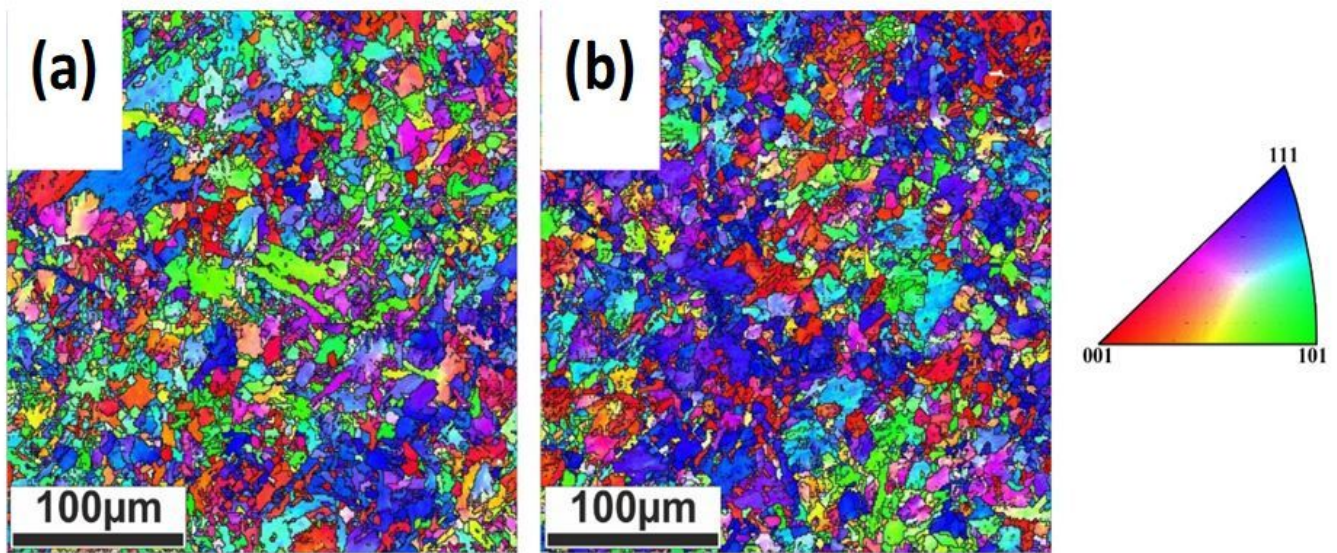


Figure 11

EBSD map for welded joints. a S3, and b S11

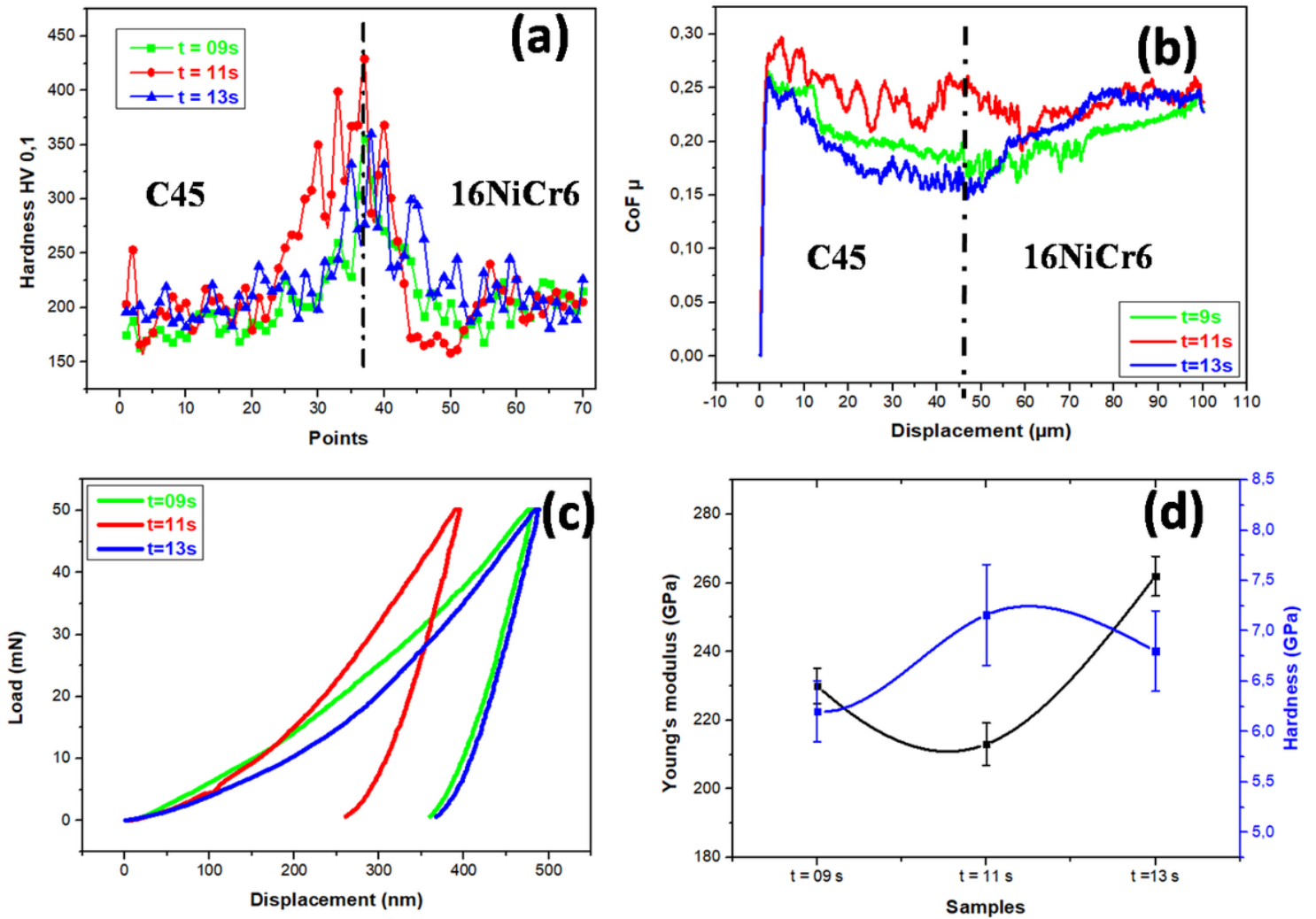


Figure 12

Influence of friction time on mechanical behavior. a Vickers micro-hardness, b scratch, c Nano-indentation, and d interaction between friction time, young's modulus (GPa) and hardness (GPa)

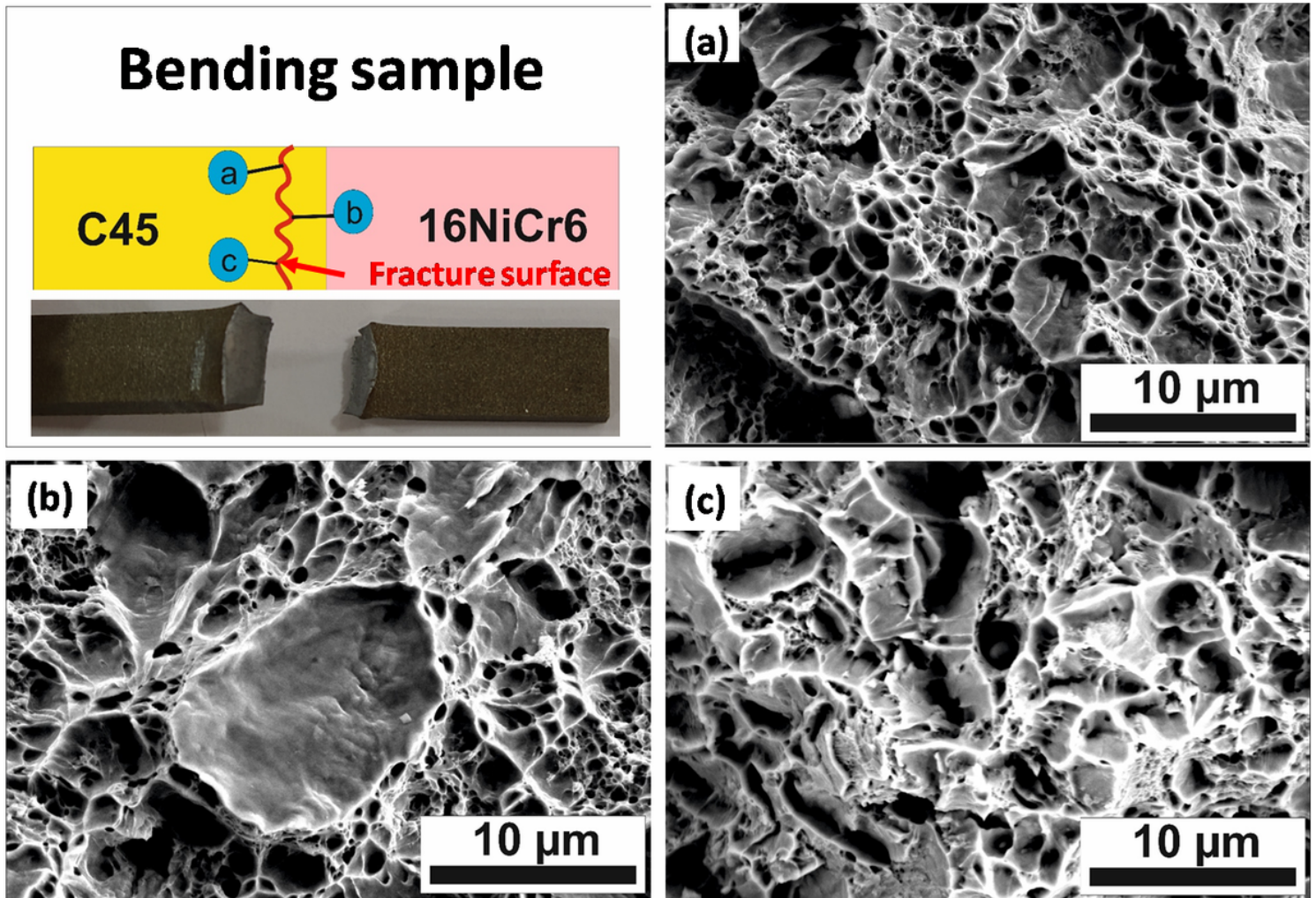


Figure 13

Bending fracture surface morphology for cracked sample

Supplementary Files

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